## In the Claims:

- 1. (original) A method of recognising an image, comprising the steps of :
  - processing the image to provide an image set containing a plurality of different processed images;
  - b. combining the processed images in the image set;
  - c. transforming the data space occupied by the processed images in the image set;
  - d. generating, from the image-set represented in the transformed data space, an image key representative of the image; and
  - e. comparing the image key with at least one previously stored image key of a known image.
- 2. (original) A method according to claim 1, wherein step a. includes extracting image features including at least one of edges, lines, wavelets, gradient components, curvature components and colour components.
- 3. (currently amended) A method according to claim 1 or 2, wherein step b. is carried out prior to step c.
- 4. (currently amended) A method according to claim 1 or 2, wherein step c. is carried out prior to step b.
- 5. (currently amended) A method according to claim 1, <del>2 or 3</del>, wherein step e. comprises comparing the image key with just one previously stored image key, to verify the identity of the image.

- 6. (currently amended) A method according to claim 1, <del>2 or 3</del>, wherein step e. comprises comparing the image key with a plurality of previously stored image keys, to identify the image.
- 7. (original) A method according to claim 6, comprising the further step of sorting the results of the comparison in step e. to produce a list of potential matches with previously stored image keys.
- 8. (currently amended) A method according to claim 6 or 7, wherein step e. is carried out using a Euclidean distance metric (the L2 norm), mahalanobis distance metric or a cosine distance metric.
- 9. (currently amended) A method according to any of the preceding claims claim 1, including the step prior to step a. of rotating and/or positioning the image to a predetermined orientation and/or position and/or depth normalisation.
- 10. (currently amended) A method according to any of the preceding claims claim 1, including a step prior to step b. of normalising data prior to combination.
- 11. (currently amended) A method according to any of the preceding claims claim 1, wherein said image is obtained from a camera.
- 12. (currently amended) A method according to any of the preceding claims claim 1, wherein said image comprises 3D data.

- 13. (currently amended) A method according to any of the preceding claims claim 1, wherein said image comprises 2D data.
- 14. (currently amended) A method according to claims 12 and 13, wherein said image comprises a registered 2D-3D image pair.
- 15. (currently amended) A method according to any of the preceding claims claim 1, wherein step c. is carried out by a Principal Component Analysis method.
- 16. (currently amended) A method according to any of claims 1 to 14 claim 1, wherein step c. is carried out by Fisher's Linear Discriminant Analysis method.
- 17. (currently amended) A method according to any of the preceding claims claim 1, wherein said image is an image of a face.
- 18. (currently amended) A method according to any of the preceding claims claim 1, wherein said image is an image of a human face.
- 19. (currently amended) A method according to any of the preceding claims claim 1, wherein said image is a natural image.
- 20. (currently amended) A method according to any of the preceding claims claim 1, wherein said image set includes the original image.
- 21. (cancelled)

- 22. (original) Apparatus for recognising an image, the apparatus comprising:
  - a. processing means arranged to process the image to provide a plurality of different processed images.
  - b. combining means arranged to combine the processed images;
  - c. reducing means arranged to reduce the data space occupied by the processed images;
  - d. generating means arranged to generate from the combined and reduced processed images an image key representative of the image; and
  - e. comparison means arranged to compare the image key with at least one previously stored image key of a known image.
- 23. (currently amended) Apparatus according to claim 21 for recognising an image, the apparatus comprising, and arranged to perform a method according to any of claims 1 to 20 claim 1:
  - a. processing means arranged to process the image to provide a plurality of different processed images.
  - b. combining means arranged to combine the processed images;
  - c. reducing means arranged to reduce the data space occupied by the processed images;
  - d. generating means arranged to generate from the combined and reduced processed images an image key representative of the image; and
  - e. comparison means arranged to compare the image key with at least one previously stored image key of a known image.

## 24. (cancelled)

- 25. (original) A method of recognising a three-dimensional image, comprising the steps of :
  - a. transforming the data space occupied by the image using Fisher's Linear Discriminant Analysis;
  - b. generating, from the transformed data space, an image key representative of the image; and
  - c. comparing the image key with at least one previously stored image key of a known image.
- 26. (original) Apparatus for recognising a three-dimensional image, the apparatus comprising:
  - a. means for transforming the data space occupied by the image using Fisher's Linear Discriminant Analysis;
  - b. means for generating, from the transformed data space, an image key representative of the image; and
  - c. means for comparing the image key with at least one previously stored image key of a known image.